

# Stochastic Process

F. M. ARIFUR RAHMAN

SENIOR LECTURER, DEPARTMENT OF MATHEMATICAL & PHYSICAL SCIENCES

# Stochastic Process

## (Random Process)

- ▶ A stochastic process  $\{X(t): t \in T\}$  is a family of random variables indexed by a parameter  $t$ , which runs over an index set  $T$ .
- ▶ The parameter  $t$  usually denotes time
- ▶ For any specific time  $t$ ,  $X(t)$  is a random variable.
- ▶ The index set  $T$  is called the parameter set.
- ▶ If  $T$  is countable,  $\{X(t)\}$  is discrete time stochastic process. If  $T$  is an interval, finite or infinite,  $\{X(t)\}$  is said to be continuous time stochastic process.
- ▶ The set of possible values of  $X(t)$  at any time  $t$  is called the state space,  $S$ .

# Stochastic Process (Random Process)

**Example:** Suppose that, a business office has five telephone lines and that any number of these lines may be in use at any time, the telephone lines are observed at regular interval of 2 minutes.

$X$ : Number of lines in use in every 2 minutes

Then for  $T=0, 1, 2, 3, \dots$ ,

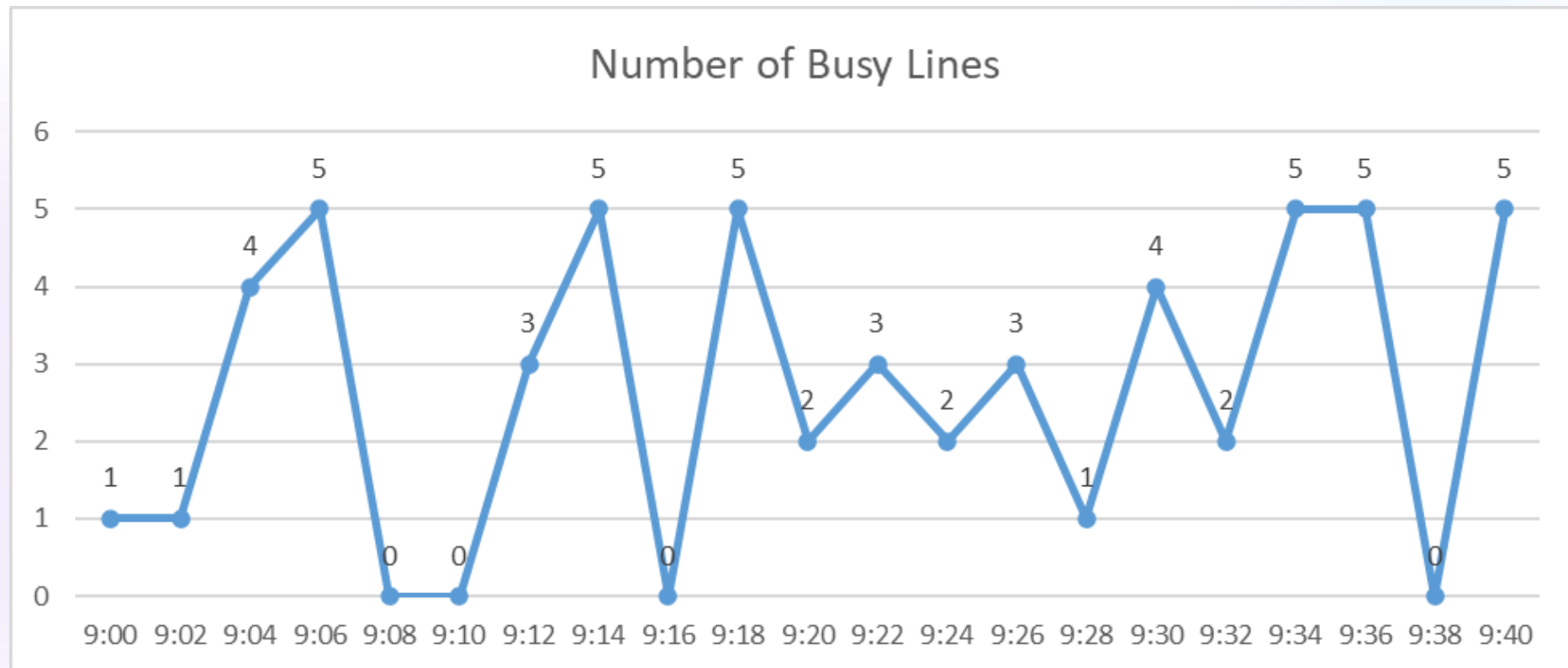
$X(t): \{X(0), X(1), X(2), \dots\}$                       e.g.  $X(t): \{3, 2, 5, 0, 1, 0, 3, \dots\}$

Here,  $\{X(t): t \in T\}$  is a stochastic process with parameter space,  $T = \{0, 1, 2, 3, \dots\}$  and State space,  $S = \{X: 0, 1, 2, 3, 4, 5\}$

# Stochastic Process (Random Process)

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An observation of this process might be one like below-



# Stochastic Process (Random Process)

**Examples of some stochastic processes:**

## 1. Random walk model:

Let,  $X_t$  is a random variable that can be any of the two states [up (+1) or down (-1)] at time  $t$ .

$X_t$	+1	-1
probability	$p$	$1-p$

Then, the process  $R_t = R_{t-1} + X_t$  is called a random walk model

## 2. Counting process

A stochastic process  $\{N(t); t > 0\}$  is a counting process if  $N(t)$  represents the total number of events that have occurred in time  $t$ .

## 3. Birth & death process

A stochastic process  $\{N(t); t \geq 0\}$  with states  $\{n = 0, 1, 2, \dots\}$  for which transition from state  $n$  may go only to either of the states  $(n-1)$  or  $(n+1)$  is a birth and death process.

# Autocorrelation (serial correlation)

- ▶ In statistics, the autocorrelation of a random process describes the correlation between values of the process at different times, as a function of the two times or of the time lag.
- ▶ Let  $X$  be some repeatable process, and  $i$  be some point in time after the start of that process. Then  $X_i$  is the value (or realization) produced by a given run of the process at time  $i$ . Suppose that the process is further known to have defined values for mean  $\mu_i$  and variance  $\sigma_i^2$  for all times  $i$ . Then the definition of the autocorrelation between times  $s$  and  $t$  is-

$$R(s, t) = \frac{E[(X_t - \mu_t)(X_s - \mu_s)]}{\sigma_t \sigma_s} = \text{Corr}(X_t, X_s)$$

# Markov Process

- ▶ Consider a finite or countably infinite set of points  $(t_0, t_1, \dots, t_n, t)$ , where  $t_0 < t_1 < \dots < t_n < t$  and  $t, t_i \in T$  ( $i = 0, 1, 2, \dots, n$ );  $T$  is a parameter space of the process  $\{x(t)\}$ .
- ▶ The dependence exhibited by the process  $\{X(t): t \in T\}$  is called Markovian dependence if the conditional distribution of  $X(t)$  for a given value of  $X(t_1), X(t_2), \dots, X(t_n)$  depends only on  $X(t_n)$ , which is the most recent known value of the process, i.e., if

$$\begin{aligned} P[X(t) = x \mid x(t_n) = x_n, X(t_{n-1}) = x_{n-1}, \dots, X(t_0) = x_0] \\ = P[X(t) = x \mid x(t_n) = x_n] \end{aligned}$$

The stochastic process exhibiting the property (Markov property) is called a Markov process.

# Markov Process

Different types of Markov process		
Parameter space	State space	
	Discrete	Continuous
Discrete	Markov Chain	Discrete parameter, continuous MP
continuous	Continuous parameter, discrete MC	Continuous parameter, continuous MP

## Notations:

$p_i$  = Probability that the process is in state  $i$

$p_{ij}^{(n)}$  =  $n$  – step transition probability of state  $j$  form state  $i$

= Probability that the process will move from state  $i$  to state  $j$  in  $n$  – steps



# Markov Process

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## Transition Probability Matrix (TPM):

A matrix containing probabilities of transition from one state to another. If there are  $k$  finite states of a Markov process, i.e.  $S = \{1, 2, \dots, k\}$ , then one-step transition probability matrix-

$$P = \begin{matrix} & \begin{matrix} 1 & 2 & \dots & k \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ \vdots \\ k \end{matrix} & \begin{bmatrix} P_{11} & P_{12} & \dots & P_{1k} \\ P_{21} & P_{22} & \dots & P_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ P_{k1} & P_{k2} & \dots & P_{kk} \end{bmatrix} \end{matrix}$$

Such that, i)  $P_{ij} \geq 0, \forall i, j \in S$ ; ii)  $\sum_j P_{ij} = 1$  (row total 1)

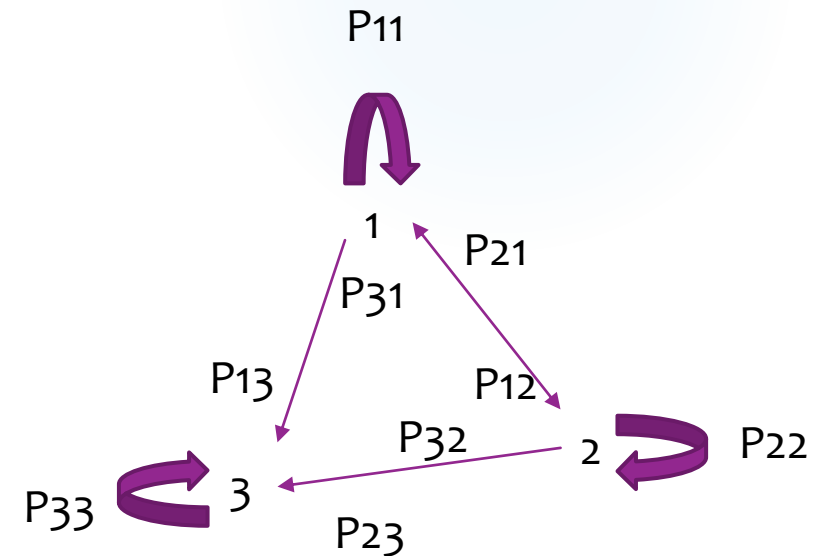
# Markov Process (Example)

## Example 1:

X= Living status. State space,  $S = \{1, 2, 3\}$ ; where, 1= Healthy, 2= Sick, 3 = Dead.

$$P = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} P_{11} & P_{12} & P_{13} \\ P_{21} & P_{22} & P_{23} \\ P_{31} & P_{32} & P_{33} \end{bmatrix} \end{matrix}$$

Here,  $P_{11} > 0, P_{12} > 0, P_{13} > 0, P_{21} > 0, P_{22} > 0, P_{23} > 0,$   
 $P_{31} = 0, P_{32} = 0, P_{33} = 1$



# Markov Process

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**Time-homogeneous Markov chains** (or stationary Markov chains) are processes where

$$P[X_{t+1} = x | X_t = y] = P[X_t = x | X_{t-1} = y]$$

for all  $t$ . The probability of the transition is independent of  $t$ .

# Markov Process

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## Classification of states:

- ▶ *Accessible state:* A state  $j$  is said to be accessible from a state  $i$  (written  $i \rightarrow j$ ) if a system started in state  $i$  has a non-zero probability ( $P_{ij} > 0$ ) of transitioning into state  $j$  at some point.
- ▶ *Communicating states:* A state  $i$  is said to communicate with state  $j$  (written  $i \leftrightarrow j$ ) if both  $i \rightarrow j$  and  $j \rightarrow i$ .
- ▶ *Absorbing state:* A state  $i$  is called absorbing if it is impossible to leave this state. Therefore, the state  $i$  is absorbing if and only if  $p_{ii} = 1$  and  $p_{ij} = 0$  for  $i \neq j$

# Markov Process

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## Classification of states:

- ▶ *Transient state & recurrent state:* A state  $i$  is said to be transient if, given that we start in state  $i$ , there is a non-zero probability that we will never return to  $i$  (the process may not return to state  $i$ ). State  $i$  is recurrent (or persistent) if it is not transient. Recurrent states are guaranteed (with probability 1) to have a finite hitting time.
- ▶ *Periodic state & aperiodic state:* A state  $i$  has period  $k$  if any return to state  $i$  must occur in multiples of  $k$  time steps. A state is said to be aperiodic if returns to state  $i$  can occur at irregular times ( $k=1$ ).

# Markov Process

## (Example)

**Example 2:** There are two telephone lines in an office and any number of these lines may be in use at any given time. During a certain point of time, telephone lines are observed at regular intervals of 2 minutes. The initial probability vector of the states is-

$$A_{1 \times K} = (0.3, 0.5, 0.2)$$

And one-step transition probability matrix is-

$$P_{K \times K} = \begin{bmatrix} 0.2 & 0.6 & 0.2 \\ 0.3 & 0.5 & 0.2 \\ 0.1 & 0.4 & 0.5 \end{bmatrix}$$

Assuming, a homogeneous Markov chain, determine the probabilities that no line, 1 line and 2 lines are being used at each of the following times: i)  $t=2$ , ii)  $t=3$ . (Assuming starting time  $t=0$ ).

# Markov Process (Example)

Let, 0: No line is in use

1: 1 line is in use

2: 2 lines is in use.

Therefore, state space,  $S=\{0, 1, 2\}$

Given that, the initial probability vector of the states is-

$$P_{1 \times K} = (0.3, 0.5, 0.2)$$

And one-step transition probability matrix is-

$$P_{K \times K} = \begin{bmatrix} 0.2 & 0.6 & 0.2 \\ 0.3 & 0.5 & 0.2 \\ 0.1 & 0.4 & 0.5 \end{bmatrix}$$

# Markov Process (Example)

i) For t=2:

$$\begin{aligned} P &= P_{1 \times K} P_{K \times K} = [0.3, 0.5, 0.2] \begin{bmatrix} 0.2 & 0.6 & 0.2 \\ 0.3 & 0.5 & 0.2 \\ 0.1 & 0.4 & 0.5 \end{bmatrix} \\ &= [0.23, 0.51, 0.26] \end{aligned}$$

i) For t=3:

$$\begin{aligned} P &= P_{1 \times K} P_{K \times K}^2 = P_{1 \times K} P_{K \times K} P_{K \times K} = [0.23, 0.51, 0.26] \begin{bmatrix} 0.2 & 0.6 & 0.2 \\ 0.3 & 0.5 & 0.2 \\ 0.1 & 0.4 & 0.5 \end{bmatrix} \\ &= [0.225, 0.497, 0.278] \end{aligned}$$



# Markov Process

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## ► Steady State Probabilities:

If for a irreducible (only one class, so that all states communicate) Markov Chain, all of the states are aperiodic and positive recurrent (it will return in a finite time), the distribution

$$A^{(n)} = A \cdot P^n$$

converges as  $n \rightarrow \infty$ , and the limiting distribution is independent of the initial probabilities, A. In general,

$$\lim_{n \rightarrow \infty} p_{ij}^{(n)} = \lim_{n \rightarrow \infty} a_j^{(n)} = p_j$$

# Markov Process

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## ► Steady State Probabilities:

Furthermore, the values  $p_j$  are independent of  $i$ . These probabilities are called steady state probabilities. These steady state probabilities  $p_j$  satisfy the following state equations-

$$p_j > 0, \dots \dots \dots (1)$$

$$\sum_{j=0}^m p_j = 1, \dots \dots \dots (2)$$

$$p_j = \sum_{i=0}^m p_i p_{ij}, \quad j = 0, 1, 2, \dots, m, \dots \dots \dots (3)$$

Since there are  $m+2$  equation in (2) & (3), and since there are  $m+1$  unknowns, one of the equations is redundant. Therefore we will use  $m$  of the  $m+1$  equations in equation (3) with equation (2).

# Markov Process

## (Example)

### Example 3:

Find steady state probabilities for the Markov chain described in example 2.

Here, for steady state,

$$(p_0 \quad p_1 \quad p_2) = (p_0 \quad p_1 \quad p_2) \begin{pmatrix} 0.2 & 0.6 & 0.2 \\ 0.3 & 0.5 & 0.2 \\ 0.1 & 0.4 & 0.5 \end{pmatrix}$$

$$\Rightarrow (p_0 \quad p_1 \quad p_2) = (0.2p_0 + 0.3p_1 + 0.1p_2 \quad 0.6p_0 + 0.5p_1 + 0.4p_2 \quad 0.2p_0 + 0.2p_1 + 0.5p_2)$$

$$p_0 = 0.2p_0 + 0.3p_1 + 0.1p_2$$

$$\Rightarrow p_1 = 0.6p_0 + 0.5p_1 + 0.4p_2$$

$$p_2 = 0.2p_0 + 0.2p_1 + 0.5p_2$$

$$\text{Also, } p_0 + p_1 + p_2 = 1$$

# Markov Process

## (Example)

Rewriting the above system of equations-

$$\begin{aligned} & -0.8p_0 + 0.3p_1 + 0.1p_2 = 0 \dots\dots\dots (1) \\ \Rightarrow & \begin{aligned} & 0.6p_0 - 0.5p_1 + 0.4p_2 = 0 \dots\dots\dots (2) \\ & 0.2p_0 + 0.2p_1 - 0.5p_2 = 0 \dots\dots\dots (3) \\ & p_0 + p_1 + p_2 = 1 \dots\dots\dots (4) \end{aligned} \end{aligned}$$

Using the equations (1), (2) & (4) we will find the steady state probabilities. First reducing the system by eliminating  $p_3$ .

$$\begin{aligned} Eq. (1) + (-0.1) \times Eq. (4) \Rightarrow & \\ & \begin{aligned} & -0.8p_0 + 0.3p_1 + 0.1p_2 = 0 \\ & -0.1p_0 - 0.1p_1 - 0.1p_2 = -0.1 \\ \hline & -0.9p_0 + 0.2p_1 \qquad \qquad = -0.1 \dots\dots (5) \end{aligned} \end{aligned}$$

# Markov Process (Example)

$$Eq. (2) + (-0.4) \times Eq. (4) \Rightarrow$$

$$\begin{array}{rcl} 0.6p_0 - 0.5p_1 + 0.4p_2 & = & 0 \\ -0.4p_0 - 0.4p_1 - 0.4p_2 & = & -0.4 \\ \hline 0.2p_0 - 0.9p_1 & = & -0.4 \dots \dots (6) \end{array}$$

$$Eq. (5) + \frac{2}{9} \times Eq. (6) \Rightarrow$$

$$\begin{array}{rcl} -0.9p_0 + 0.2p_1 & = & -0.1 \\ \frac{0.4}{9}p_0 - 0.2p_1 & = & -\frac{0.8}{9} \\ \hline -0.9p_0 + \frac{0.4}{9}p_0 & = & -0.1 - \frac{0.8}{9} \\ \Rightarrow 0.77p_0 = 0.11 & \Rightarrow & p_0 = \frac{11}{77} \end{array}$$

# Markov Process (Example)

*From Eq. (5),*

$$\begin{aligned} -0.9p_0 + 0.2p_1 &= -0.1 \\ \Rightarrow p_1 &= -\frac{1}{2} + \frac{9}{2}p_0 = \frac{38}{77} \end{aligned}$$

*From Eq. (4),*

$$\begin{aligned} p_0 + p_1 + p_2 &= 1 \\ \Rightarrow p_2 &= 1 - \frac{55}{77} = \frac{22}{77} \end{aligned}$$

So, the steady state probabilities for the above stated Markov chain are-  $p_0 = \frac{17}{77}$ ,  $p_1 = \frac{38}{77}$ ,  
 $p_2 = \frac{22}{77}$